

IN THE CLAIMS

Please amend the claims as set out in the following listing of the claims, which claim listing supersedes and replaces all prior listings of the claims:

1-5 (Canceled).

6. (Currently Amended) The robot apparatus charging system according to claim [[4]] 36, characterized in that said robot apparatus has a head, and said predetermined movement is a movement to raise said head.

7. (Canceled)

8. (Currently Amended) The robot apparatus charging system according to claim [[4]] 36, characterized in that said robot apparatus has a tail, and said predetermined movement is a movement to wag said tail.

9-16 (Canceled)

17. (Currently Amended) The robot apparatus according to claim [[15]] 44, characterized in that said robot apparatus has a head, and said predetermined movement is a movement to raise said head.

18. (Canceled)

19. (Currently Amended) The robot apparatus according to claim [[15]] 44, characterized in that said robot apparatus has a tail, and said predetermined movement is a movement to wag said tail.

20-35 (Canceled)

36. (Previously presented) A robot apparatus, comprising:

movement generating means for generating a movement;

detection means for detecting that a predetermined area is rocked; and

control means for controlling said movement generating means, characterized in that when it is recognized that said predetermined area is rocked on the basis of a detection result of said detection means in a state in which generation of said movement is stopped, said control means controls said movement generating means to start generation of said movement wherein said predetermined area is a body portion of the robot apparatus.

37-43 (Canceled)

44. (Previously Presented) A robot apparatus charging system, comprising:

a robot apparatus on which a charging battery is mounted, and

a charging device for charging said charging battery mounted on said robot

apparatus,

wherein said robot apparatus includes charging indicating means for performing a predetermined movement of at least one selected body part of the robot apparatus to indicate an amount of charging in said charging battery on charging said charging battery in said charging device,

said at least one selected body part of said robot apparatus has a movable portion and said predetermined movement is a movement to move said movable portion, and

wherein said predetermined movement is a movement to change a pose of said robot apparatus from a first pose during charging to a second pose to notify of completion of charging by moving said movable portion at completion of charging of said charging battery.

45. (Previously Presented) The robot apparatus charging system according to claim 44, characterized in that said predetermined movement is a movement to notify of completion of charging of said charging battery, said robot apparatus has a head, and said predetermined movement is a movement to raise said head.

46. (Previously Presented) The robot apparatus charging system according to claim 45, characterized in that said robot apparatus has forelegs and hind legs, and said predetermined movement is a movement to lift said forelegs.

47. (Previously Presented) The robot apparatus charging system according to claim 45, characterized in that said robot apparatus has a tail, and said predetermined movement is a movement to wag said tail.

48. (Previously Presented) The robot apparatus charging system according to claim 45, characterized in that said robot apparatus has legs, and said predetermined movement is a movement to raise said legs.

49. (Previously Presented) The robot apparatus charging system according to claim 45, characterized in that said robot apparatus has a speaker, and said predetermined movement is a movement to make a sound through said speaker.

50. (Previously Presented) The robot apparatus charging system according to claim 45, characterized in that said robot apparatus has voice generating means for generating a predetermined voice and a speaker, and said predetermined movement is a movement to output said voice generated by said voice generating means through said speaker.

51. (Previously Presented) A robot apparatus comprising charging indicating means for performing, on charging a charging battery mounted thereon, a predetermined movement of at least one selected a body part of the robot apparatus to indicate an amount of charging of said charging battery during charging of said charging battery in a charging device,

wherein said selected body part of said robot apparatus has a movable portion and said predetermined movement is a movement to move said movable portion, and

said predetermined movement is a movement to change a pose of said robot apparatus from a first pose during charging to a second pose to notify of completion of charging by moving said movable portion at completion of charging of said charging battery.

52. (Previously Presented) The robot apparatus according to claim 51, characterized in that said predetermined movement is a movement to notify of completion of charging of said charging battery.

53. (Previously Presented) The robot apparatus according to claim 52, characterized in that said predetermined movement is a continuous movement.

54. (Previously Presented) The robot apparatus according to claim 52, characterized in that said robot apparatus has a head, and said predetermined movement is a movement to raise said head.

55. (Previously Presented) The robot apparatus according to claim 52, characterized in that said robot apparatus has forelegs and hind legs, and said predetermined movement is a movement to lift said forelegs.

56. (Previously Presented) The robot apparatus according to claim 52, characterized in that said robot apparatus has a tail, and said predetermined movement is a movement to wag said tail.

57. (Previously Presented) The robot apparatus according to claim 52, characterized in that said robot apparatus has legs, and said predetermined movement is a movement to raise said legs.

58. (Previously Presented) The robot apparatus according to claim 52, characterized in that said robot apparatus has a speaker, and said predetermined movement is a movement to make a sound through said speaker.

59. (Previously Presented) The robot apparatus according to claim 52, characterized in that said robot apparatus has voice generating means for generating a predetermined voice and a speaker, and said predetermined movement is a movement to output said voice generated by said voice generating means through said speaker.

60. (Canceled)

61. (Currently Amended) ~~The A~~ robot apparatus charging method ~~according to claim 60,~~ for charging a charging battery mounted on a robot apparatus, characterized by causing charging indicating means of said robot apparatus, on charging said charging battery in a charging device, to perform a predetermined movement of at least one selected body part of said robot apparatus to indicate an amount of charging of said charging battery while said robot apparatus is in a charging device, said robot apparatus is caused to perform a predetermined movement at completion of charging of said charging battery, and

said predetermined movement is a movement to notify of completion of charging of said charging battery characterized in that said robot apparatus has a head, and said predetermined movement is a movement to raise said head.

62. (Canceled)

63. (Currently Amended) ~~The A~~ robot apparatus charging method ~~according to claim 60,~~ for charging a charging battery mounted on a robot apparatus, characterized by causing charging indicating means of said robot apparatus, on charging said charging battery in a charging device, to perform a predetermined movement of at least one selected body part of said

robot apparatus to indicate an amount of charging of said charging battery while said robot apparatus is in a charging device, said robot apparatus is caused to perform a predetermined movement at completion of charging of said charging battery, and

said predetermined movement is a movement to notify of completion of charging of said charging battery characterized in that said robot apparatus has a tail, and said predetermined movement is a movement to wag said tail.

64-66 (Canceled)